

Analysis of the phase shift error between A and B signals in BPMs

BPM project

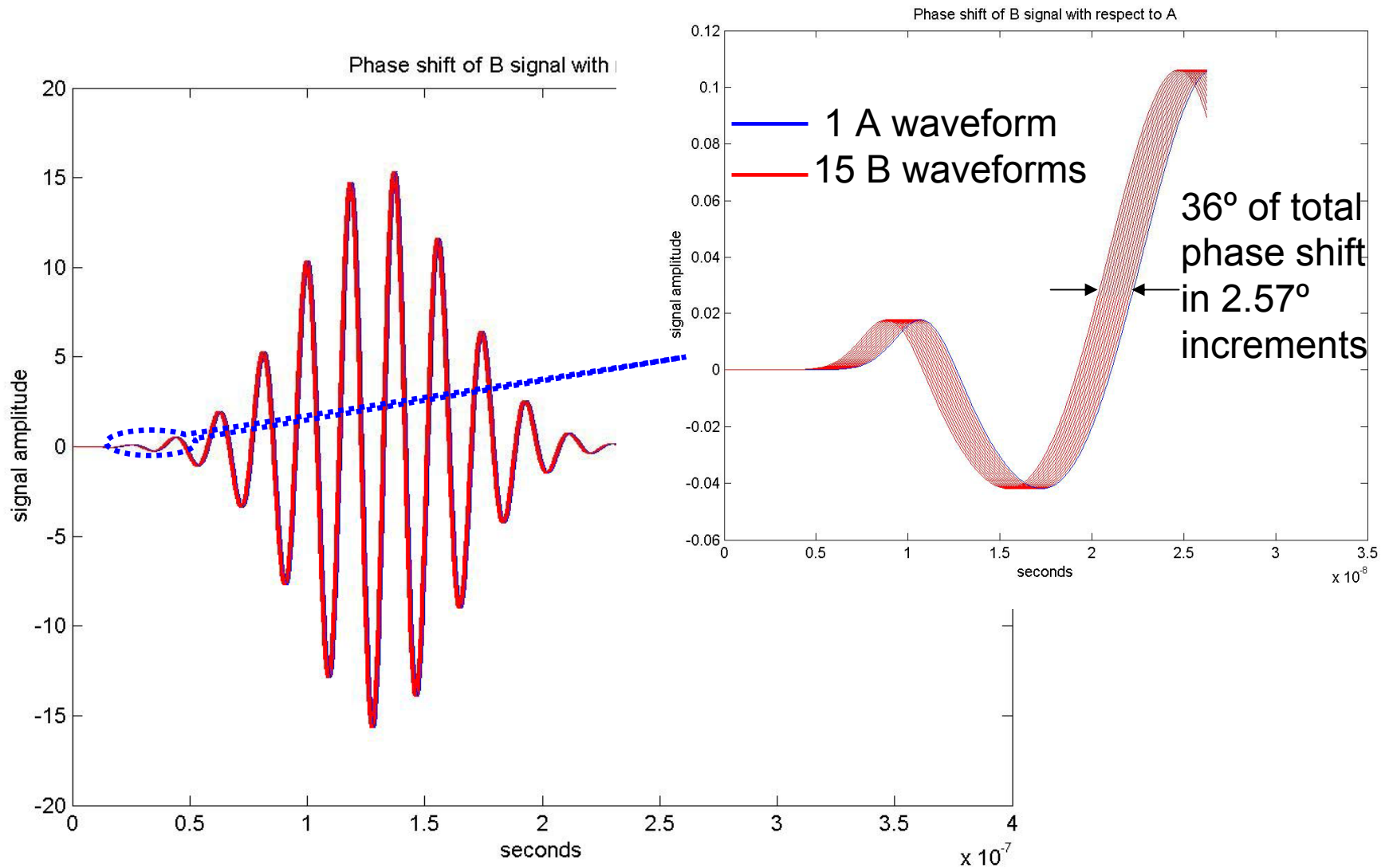
The phase shift problem

- A phase shift between A and B signals may arise do to different time propagation delays of A and B in the front-end electronics.
 - The propagation time in cables is $\sim 1\text{ns/ft}$.
 - A to B cable length mismatch of 1.5cm generates a phase shift of 1 degree.
- A and B signals are individually processed by analog filters. Different relative phases in the analog filters will generate an A to B phase shift.

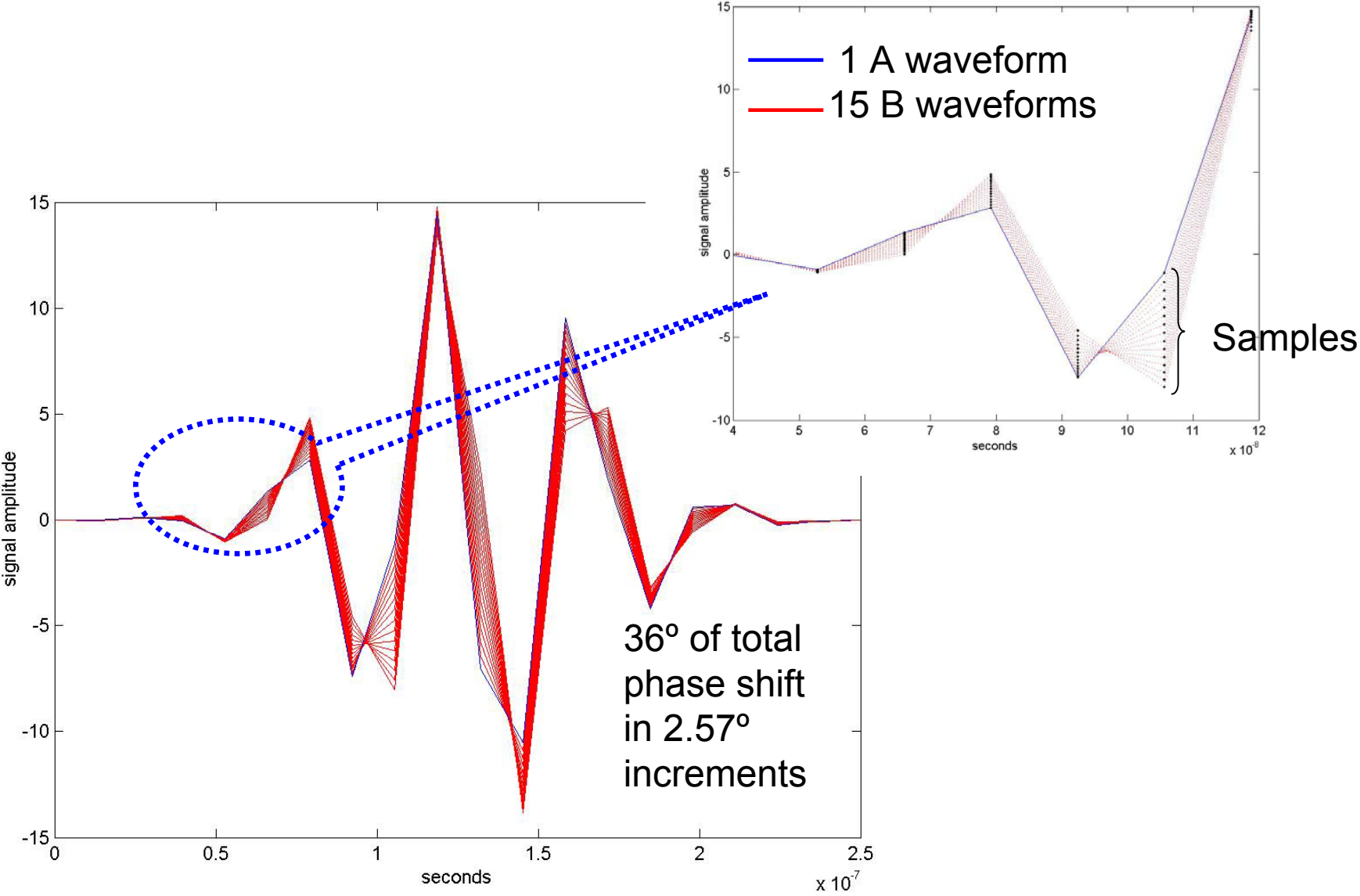
A to B signal shift simulation

- The phase of B is advanced with respect to the phase of A in steps of 2.57° (degrees) in the interval $[0^\circ, 36^\circ]$.
- The simulation computes the error in position calculation as a function of the phase shift.

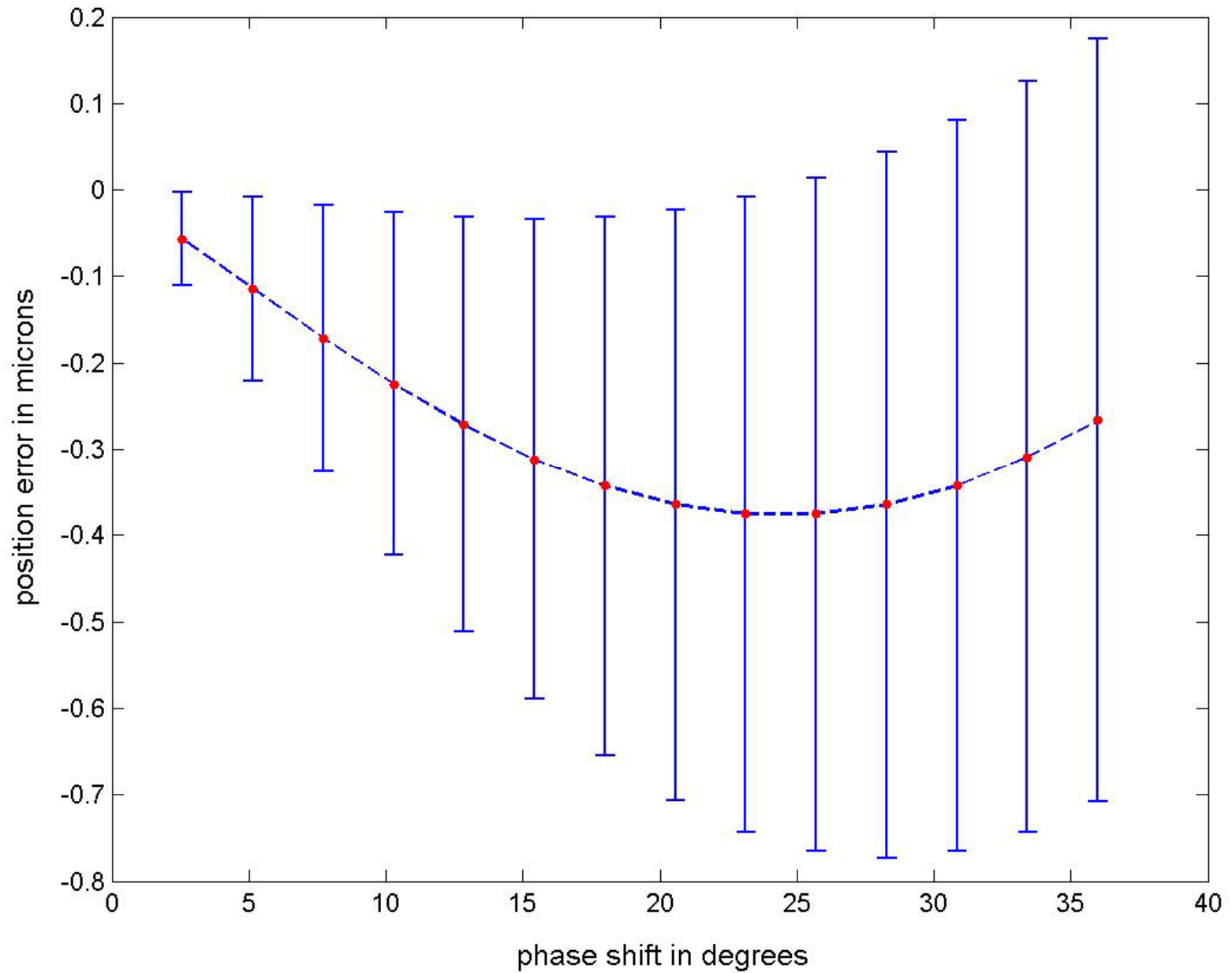
A and shifted B plots at high sampling frequency



Plots of A and shifted B, sampled at 74MHz

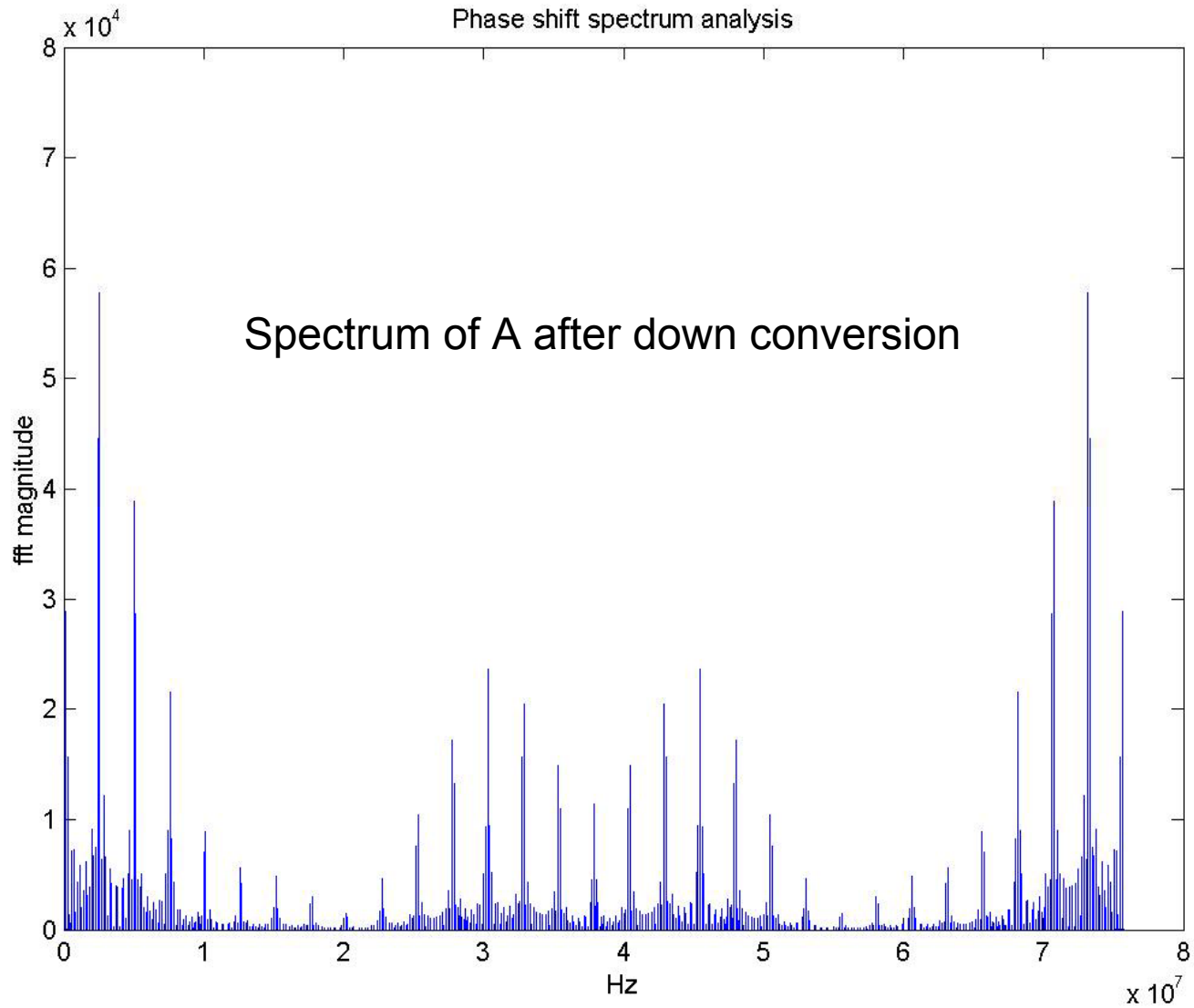


Position error simulation

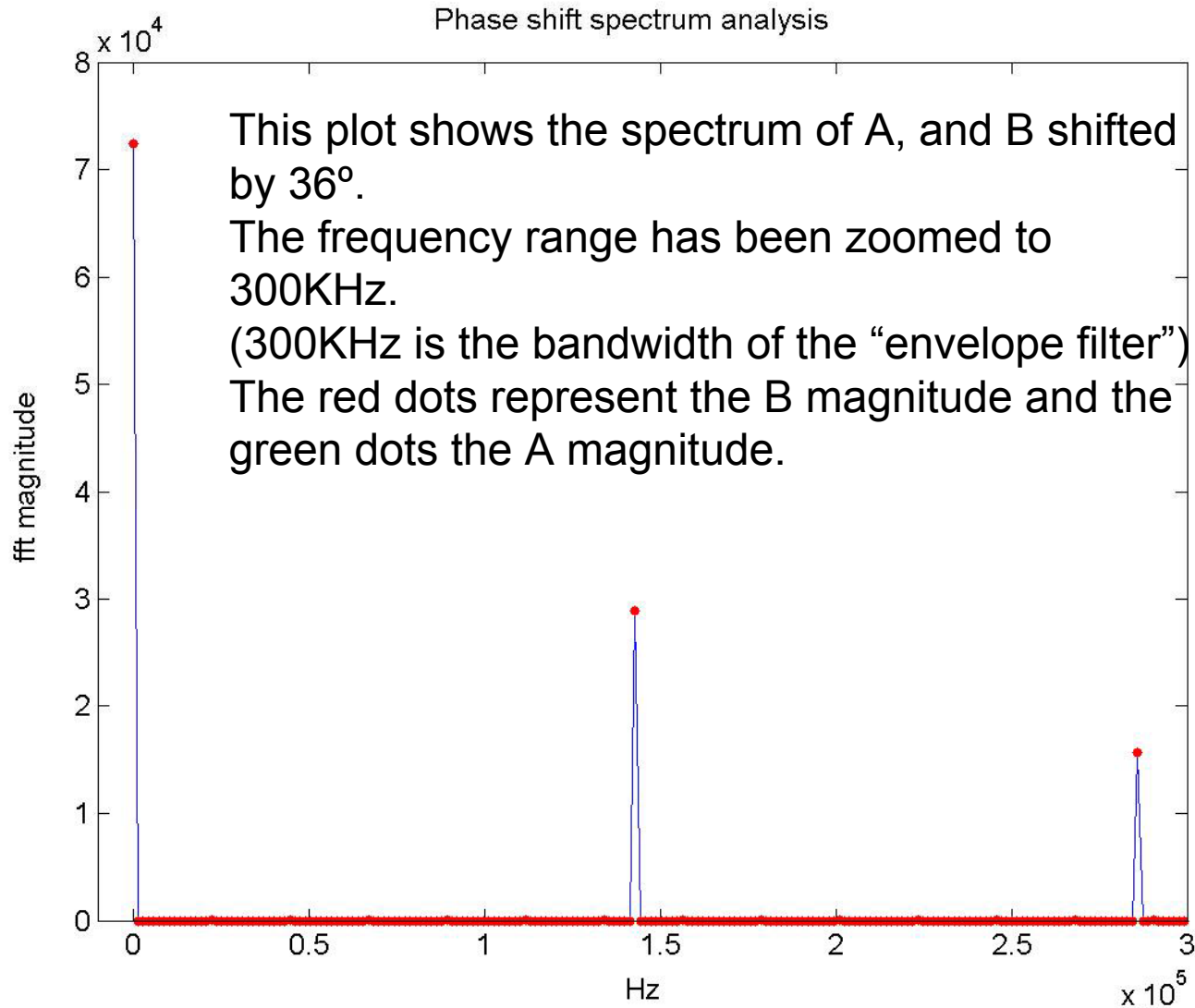


Gustavo Cancelo

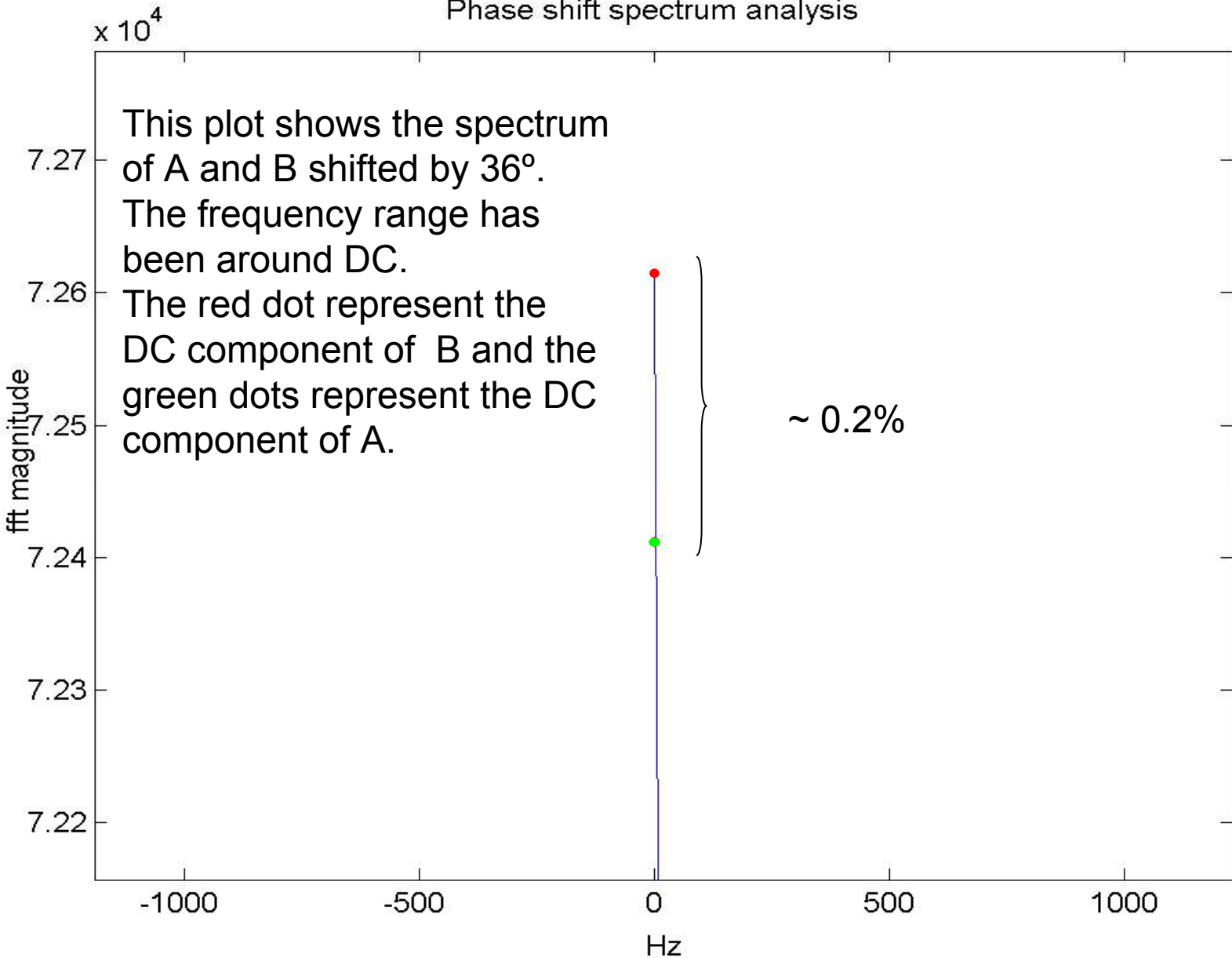
Spectrum analysis



Spectrum analysis



Phase shift spectrum analysis



Model of the shift problem

Signal model:

$$a(t) = A \left[e^{-(t/\sigma_s)^2} - e^{-(t-t_0)^2/\sigma_s^2} \right] \quad b(t) = B \left[e^{-(t+\Delta t/\sigma_s)^2} - e^{-(t+\Delta t-t_0)^2/\sigma_s^2} \right]$$

Fourier transforms:

$$A(\omega) = \sqrt{\pi} A \sigma_s \left[1 - e^{-j\omega t_0} \right] e^{-(\pi \sigma_s \omega)^2} \quad B(\omega) = \sqrt{\pi} B \sigma_s \left[e^{-j\omega \Delta t} - e^{-j\omega(t_0 + \Delta t)} \right] e^{-(\pi \sigma_s \omega)^2}$$

Ringling filter model for time and frequency domains:

$$h(t) = h_0 e^{-(t-t_0)^2/\sigma^2} \cdot \cos(\omega_c t + \phi) \quad H(\omega) = h_0 \sqrt{\pi} \sigma e^{-\frac{\sigma^2 \omega_c^2}{4}} e^{-\pi^2 \sigma^2 \left(\omega - \frac{\omega_c}{4\pi^2} \right)^2} \cdot \cos(\omega_c t_0 + \phi)$$

Signal at the output of the ringling filter (frequency domain)

$$U_A(\omega) = U_{0A} \left[1 - e^{-j\omega t_0} \right] e^{-\pi^2 \sigma^2 \left(\omega - \frac{\omega_c}{4\pi^2} \right)^2} \quad \text{where} \quad U_{0A} = H_0 \sqrt{\pi} A \sigma_s e^{-\pi^2 \sigma_s^2 \left(\frac{\omega_c}{4\pi^2} \right)^2}$$

$$U_B(\omega) = U_{0B} \left[e^{-j\omega \Delta t} - e^{-j\omega(t_0 + \Delta t)} \right] e^{-\pi^2 \sigma^2 \left(\omega - \frac{\omega_c}{4\pi^2} \right)^2} \quad \text{where} \quad U_{0B} = H_0 \sqrt{\pi} B \sigma_s e^{-\pi^2 \sigma_s^2 \left(\frac{\omega_c}{4\pi^2} \right)^2}$$

The shift shows as phase information

Model of the shift problem

Let's assume that the signal is filtered using an ideal filter with a cutoff freq. = ω_0 (e.g. $\omega_0 = 2 \cdot \pi \cdot 300 \text{KHz}$) and unit gain.

$$V_A(\omega) = U_A(\omega) \cdot W(\omega) = U_{0A} \cdot \left[1 - e^{-j\omega t_0} \right] e^{-\pi^2 \sigma^2 \left(\omega - \frac{\omega_c}{4\pi^2} \right)^2}$$

$$V_B(\omega) = U_B(\omega) \cdot W(\omega) = U_{0B} \cdot \left[e^{-j\omega \Delta t} - e^{-j\omega(t_0 + \Delta t)} \right] e^{-\pi^2 \sigma^2 \left(\omega - \frac{\omega_c}{4\pi^2} \right)^2}$$