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Thoughts on Tev BPM's

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Tev detector

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- Stripline
- Two plates 110° wide
- 7.250" long
- 35mm plate radius

$$x \approx R \frac{A - B}{A + B} \approx R \log \frac{A}{B} = \frac{R}{20} \left. \frac{A}{B} \right|_{db}$$

accepted values :

$$x \approx 26 \left(\frac{A - B}{A + B} \right) \quad \text{or} \quad x \approx 1.5 \frac{mm}{db} \left(\left. \frac{A}{B} \right|_{db} \right)$$

- Provides ok position near center...



Sinusoidal beam current

- Voltage output is the sum of the signals produced at the ends and is proportional to beam current and plate impedance
- For a sinusoidal beam current (at the upstream end):

$$\frac{V_{plate}}{I_{beam}} = \frac{Z_o}{2} \frac{110^\circ}{360^\circ} \left\{ \sin \omega \left(t + \frac{\Delta t}{2} \right) - \sin \omega \left(t - \frac{\Delta t}{2} \right) \right\}$$

$$\Delta t = \frac{2l}{c} \quad \text{for plate length } l$$

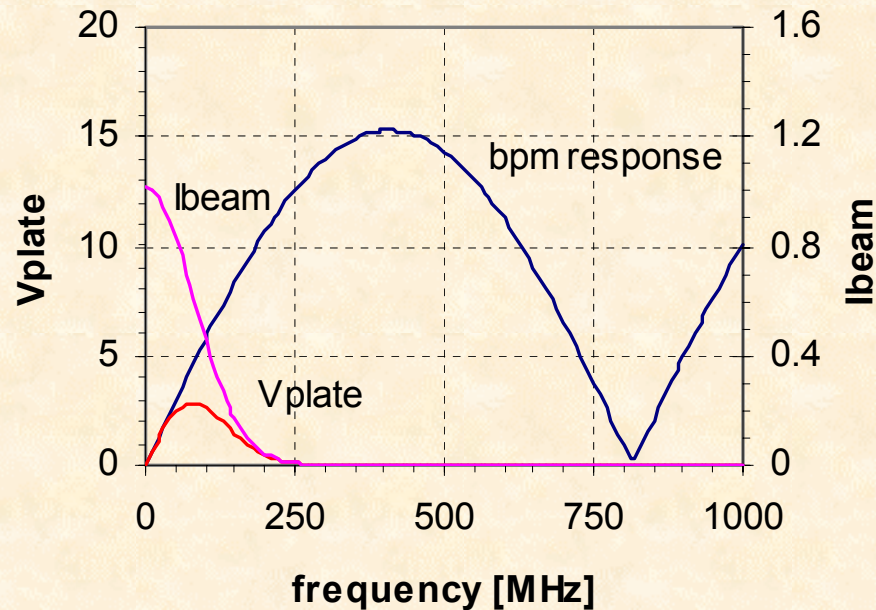
$$\frac{V_{plate}}{I_{beam}} = Z_o \frac{110^\circ}{360^\circ} \sin \omega \frac{l}{c} \cos \omega t$$



Continuous gaussian bunch train

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- 53MHz spacing, 2ns σ , $6e10$ /bunch, 50Ω plate
 - Peak response at 407MHz (plate is $\lambda/4$ long)
 - peak signal at 80MHz



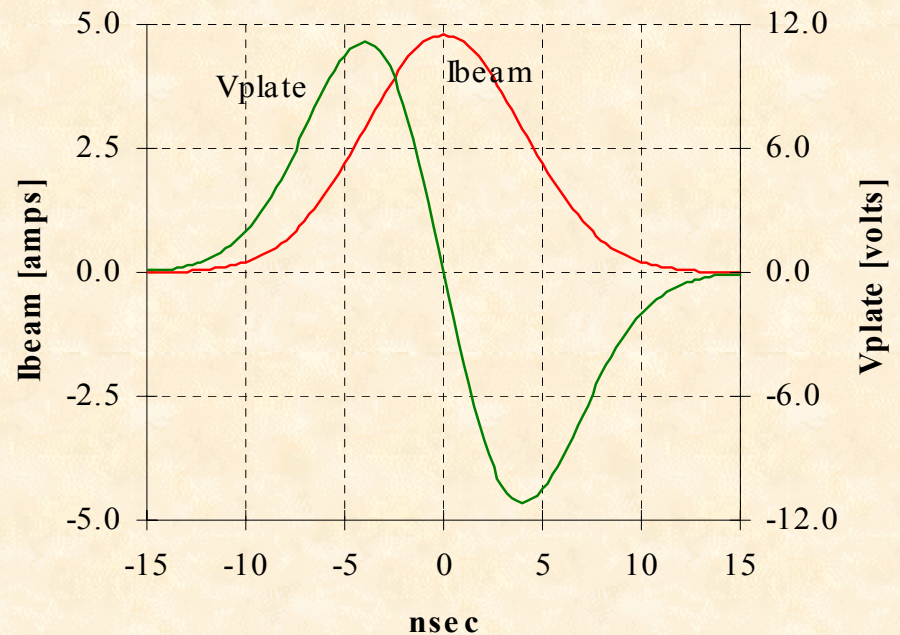


Single gaussian bunch

- Single gaussian bunch, 4ns σ_t , $3e11$, 50Ω plate
 - Plate length 7.25'' ($dt = 2l/c = 1.2\text{nsec}$)
 - $I_{\text{beam}} = 4.8\text{Amps peak}$, $V_{\text{plate}} = 11\text{Volts peak}$

$$I = \frac{Ne}{\sigma_t \sqrt{2\pi}} \exp\left[-\frac{1}{2}\left(\frac{t}{\sigma_t}\right)^2\right]$$

$$\frac{dI}{dt} = \frac{Ne}{\sigma_t \sqrt{2\pi}} \exp\left[-\frac{1}{2}\left(\frac{t}{\sigma_t}\right)^2\right] \frac{t}{\sigma_t^2}$$





Effect of noise

- For N samples of a 14 bit digitizer
- 14 bit converter has 74db SINAD
 - SINAD = signal to noise and distortion
 - 74db/20log2 = 12.4bits ENOB (effective number of bits)

$$\frac{V_{noise}}{V_{plate}} \approx \frac{1}{\sqrt{N}} \frac{1}{2^{bits}} \frac{1}{\sqrt{2}}$$

$$X \approx r \frac{A - B}{A + B} \quad r \approx \text{radius of the plates}$$

$$V_{A \text{ noise}} \pm V_{B \text{ noise}} = \sqrt{2} V_{noise}$$

$$X_{noise} \approx r \frac{\sqrt{2} V_{noise}}{A + B}$$

for $A = B$

$$X_{noise} = \frac{r}{\sqrt{2}} \frac{V_{noise}}{V_{plate}}$$

- (Non-linearity error does not improve with the number of samples)



Position noise with 84 bunch train

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- For a signal that just reaches full scale input of a 14 bit A/D, 70MHz sample rate, measuring 84 - 53MHz bunches (N=111 samples)

$$X_{noise} = \frac{26}{\sqrt{2}} \frac{1}{\sqrt{111}} \frac{1}{2^{13}} = 0.22 \mu m \text{ Rms}$$

- Position noise is inversely proportional to the beam intensity and the square root of the number of samples
- Cable loss will decrease the signal
 - 1.2db/100ft at 50MHz x 700ft = 8.4db (x 2.6)
 - Long cable with 20 bunches at 1% of the intensity
 - $X_{noise} = 117 \mu m \text{ Rms}$



Measuring single coalesced bunch

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- Use a narrow band filter (or comb filter) to ring
 - Smooths and stretches the signal out
- Simple RLC filter time constant $t_f = 2Q/2\pi f_0$
 - Measure about Q/π periods
 - Number of samples = $f_s * t_f = 8.4$
 - For $f_s=70\text{MHz}$, $f_0=53\text{MHz}$, $Q=20$
 - Assuming the signal matches full scale of the A/D...

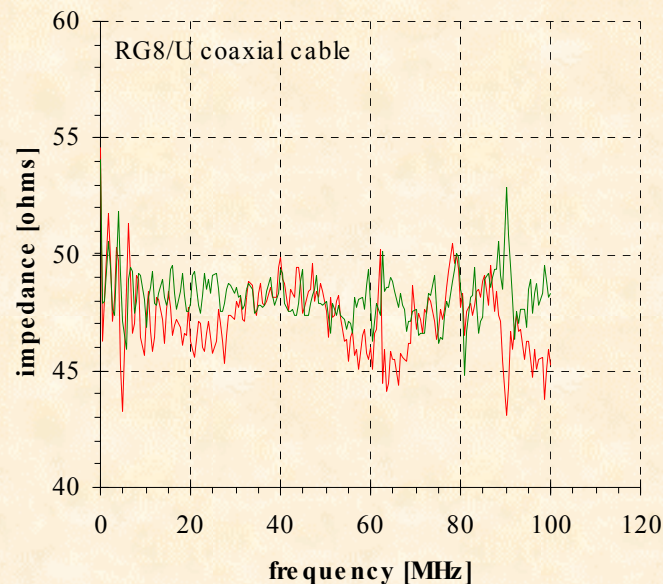
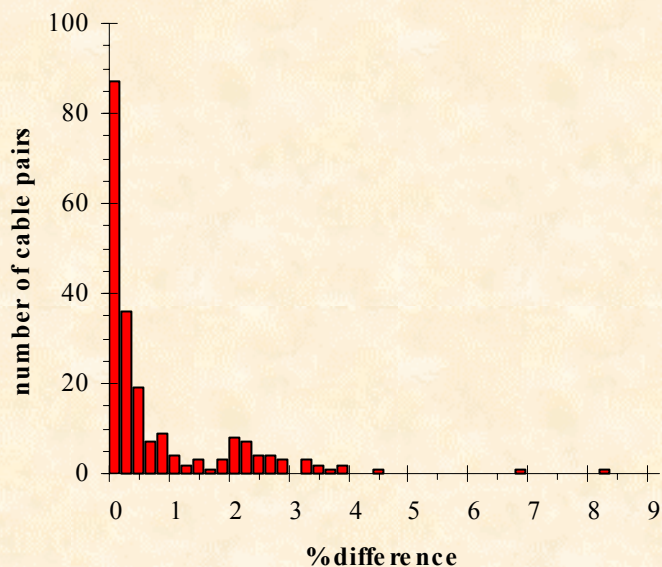
$$X_{noise} = \frac{26}{\sqrt{2}} \frac{1}{\sqrt{8.4}} \frac{1}{2^{13}} = 0.77 \mu m$$

- (Bunches must be separated by several t_f)



Main Injector RG8/U cable

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- Measured the length of all 416 cables and plotted distribution of percentage differences
- Also measured characteristic impedance of a few cables
- Manufacturer's specifications:
 - $v/c = 78 \pm 1\%$ $Z_0 = 50 \pm 2\Omega$



Effect of impedance matching

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- Assuming $kr \ll 1$ and that $A \approx B$

$$k_r = \frac{Z - Z_0}{Z + Z_0} \quad A' = A(1 + k_r)$$

$$x \approx r \frac{A(1 + k_r) - B}{A + B}$$

$$X_{error} \approx \frac{r}{2} k_r$$

- For $Z - Z_0 = 5\Omega$, $kr = .05$
 - $X_{error} = 0.66\text{mm}$



Cable attenuation

- The percentage change in attenuation is probably about the same as the percentage change in characteristic impedance

$$\alpha \left[\frac{Np}{m} \right] = \frac{R}{2Z_o}$$

- For a 5Ω or 10% variation in Z_o

$$X = 1.5 \left[\frac{mm}{db} \right] 20 \log \left(\frac{A(1 \pm 0.1)}{B} \right)$$

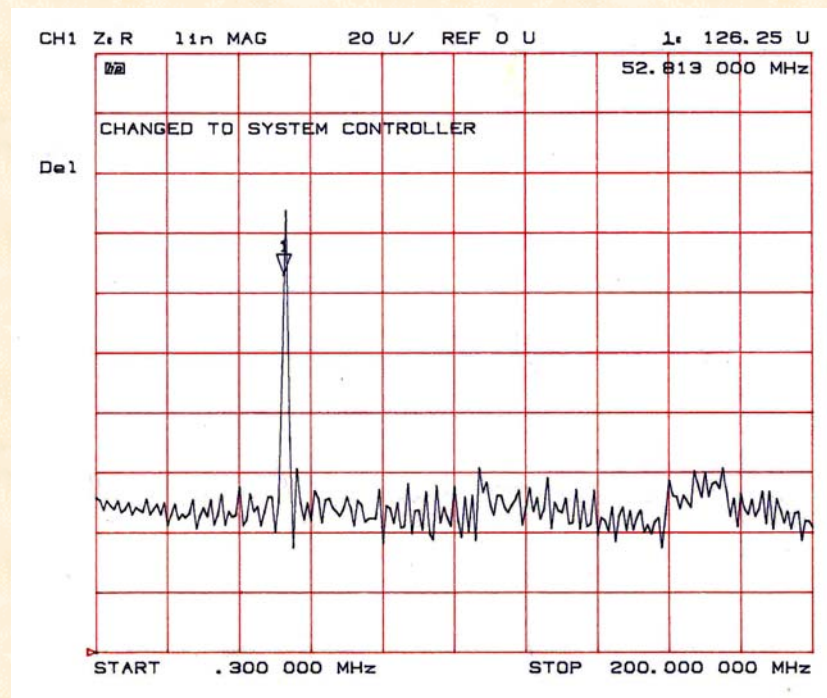
$$X_{error} = 1.5 \left[\frac{mm}{db} \right] 20 \log(1 \pm 0.1) = 1.2mm$$



VP801 cable problem

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- Getting unstable positions from one location in MI8 beam line
- The cable on one plate had impedance bump at 53MHz?!





MI8bpm problem

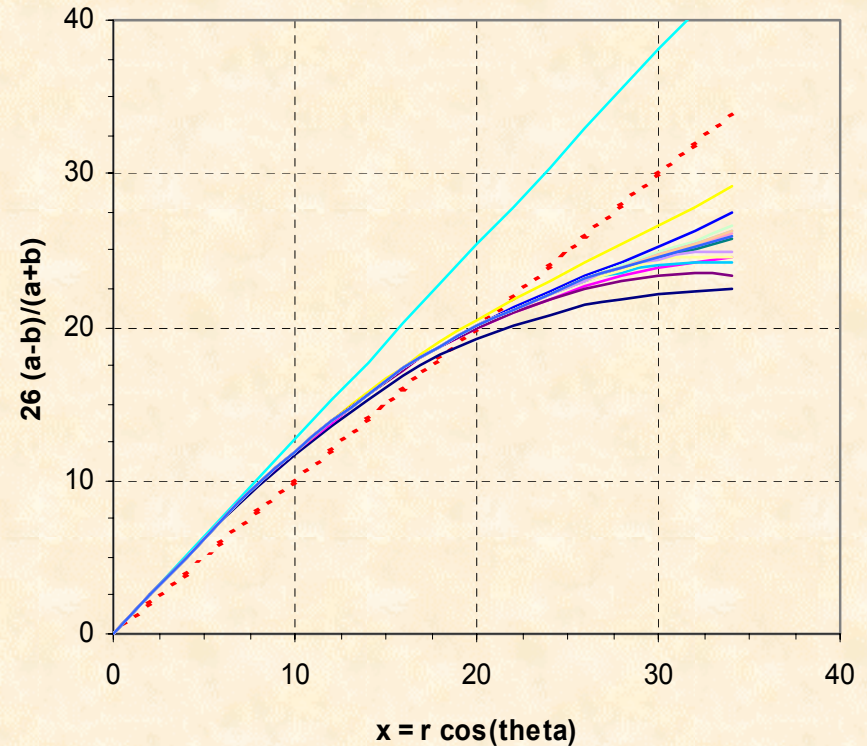
- possibility: The cable reel sat on one side making a periodic deformation or change in Z_0 ?
- $\frac{1}{2}$ wavelength corresponds to 2.3ft diameter reel
 - About right
- nearby bpm's had similar “bumps” at higher and lower frequencies.
 - Could be different layers from same reel
- Something in the manufacturing process?
 - Manufacturer says no way



Effect of nonlinear BPM's

- Radial position r at angle θ in bpm of radius b with plate width a ($n = 1$ to 26)

$$\frac{I_A}{I_{beam}} = \frac{\phi}{2\pi} \left\{ 1 + \sum_{n=1}^{\infty} \frac{4}{n\phi} \left(\frac{r}{b}\right)^n \cos(n\theta) \sin\left(n\frac{\phi}{2}\right) \right\}$$
$$\frac{I_B}{I_{beam}} = \frac{\phi}{2\pi} \left\{ 1 + \sum_{n=1}^{\infty} \frac{4}{n\phi} \left(\frac{r}{b}\right)^n \cos(n\theta) \sin\left(n\left(\pi + \frac{\phi}{2}\right)\right) \right\}$$



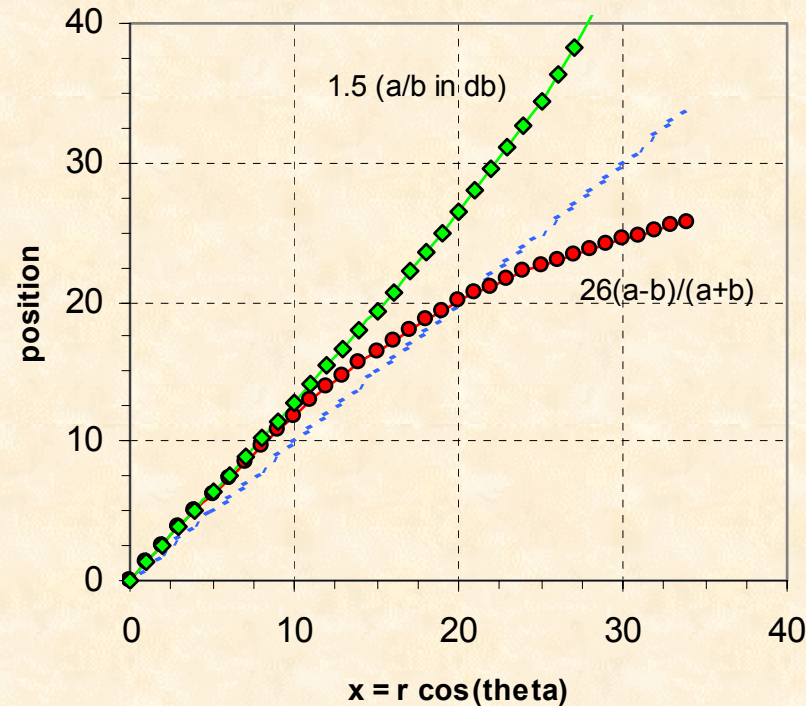
- (Convolve transverse bunch shape with bpm response to obtain position)



Compare diff/sum with log ratio

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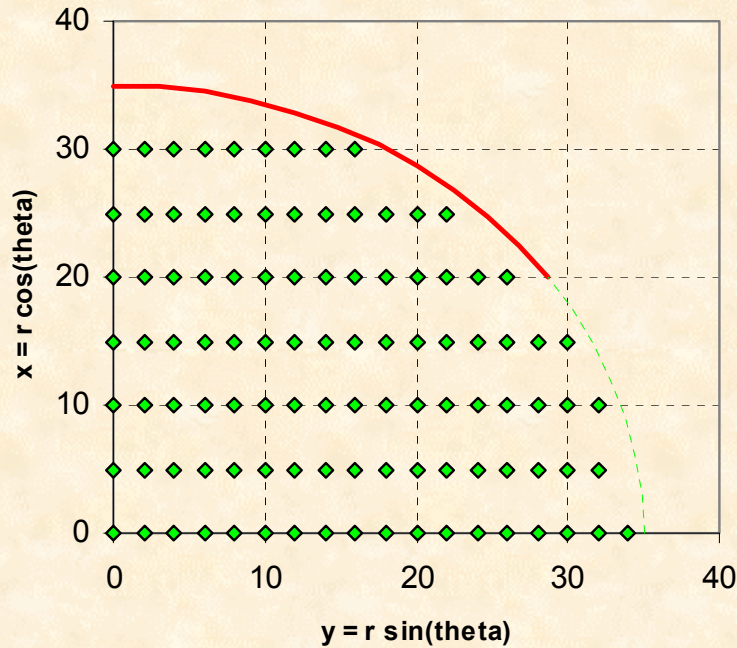
- From calculated bpm signals at the center of the orthogonal plane



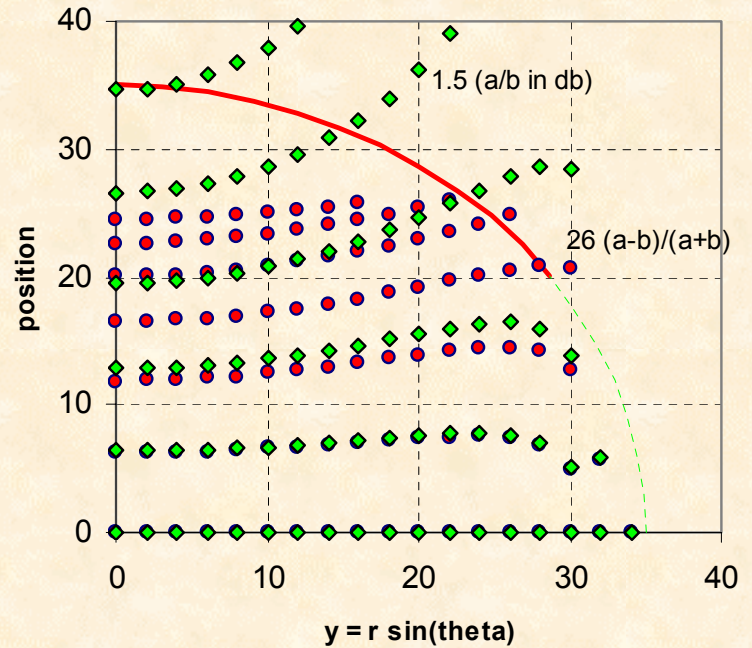


Scan over aperture

- Simulated beam positions



- position using diff/sum and log ratio scaling





Linearity and Directionality

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- So far we have assumed the plates do not talk to each other
- In reality, the plates have different common mode and differential mode characteristic impedance.
 - For the beam at the center, the plate signals will be identical and things work as described.
 - For an off center beam, the signals will not be the same and the impedance will be less
 - I believe this causes the non-linear response of the bpm
 - Gain and directionality are a function of beam position
- (We can build a perfect detector only if the beam doesn't move off center)



Directionality

- The voltage at the downstream end of the stripline is the sum of the signals produced at the ends
 - However, at the downstream end, the signals arrive at the same time ($\Delta t = 0$)

$$\frac{V_{plate}}{I_{beam}} = \frac{Z_0}{2} \frac{110^\circ}{360^\circ} \left\{ \sin \omega \left(t + \frac{\Delta t}{2} \right) - \sin \left(t - \frac{\Delta t}{2} \right) \right\} = 0$$

- This happens iff
 - the beam velocity matches the velocity of the signal on the plate
 - The beam induced signals at the ends exactly cancel
- The Tev bpm's are said to have a directionality of 26db
 - The signal on the downstream end is about 1/20th of the upstream signal
 - (changes a lot with frequency and beam position)
 - It can never be better than the error caused by plate to cable impedance match
 - (cable impedance changes by 10% which changes signal amplitude by 5% resulting in 26db directionality)



VSWR

- VSWR – voltage standing wave ratio
 - Ratio of the max to the min voltage along a cable that is not properly terminated

$$vswr = \rho = \frac{1 + |k_r|}{1 - |k_r|} \quad k_r = \frac{Z - Z_o}{Z + Z_o}$$

$$\rho = \text{larger of } \frac{Z}{Z_o} \text{ or } \frac{Z_o}{Z} \quad (\text{always greater than 1})$$

- Assume both cables have the same vswr but max and min's probably don't align at the receiver
 - Use the square root of the vswr to estimate position error

$$X = 1.5 \left[\frac{mm}{db} \right] 20 \log \left(\frac{A}{B} \sqrt{\rho} \right)$$

$$X_{error} = 1.5 \left[\frac{mm}{db} \right] 20 \log(\sqrt{\rho}) = 0.6mm \text{ for } \rho = 1.1$$



Reflections

- The Tev bpm cables range from 200 to 700 feet.
- Reflections will be separated by 400 to 1400 nsec.
- The amplitude of the reflections will be about 5% and will depend on frequency content of the beam
 - .42db or .64mm error
- In general, a kicker gap is required and necessitates a gap in the beam
 - Best if position is measured from beam following one of these gaps



State of the art

- position is about 1.5mm/db
- \$35k HP network analyzer
 - 0.04db (60um)
 - reasonably soon after a full 2 port cal using short well behaved cables with good quality connectors in a nice quiet lab environment
- 1 bit error on full scale 14 bit A/D is .00053db (0.8um)
 - Noise might be this good but, accuracy will not be!



Thoughts on receiver

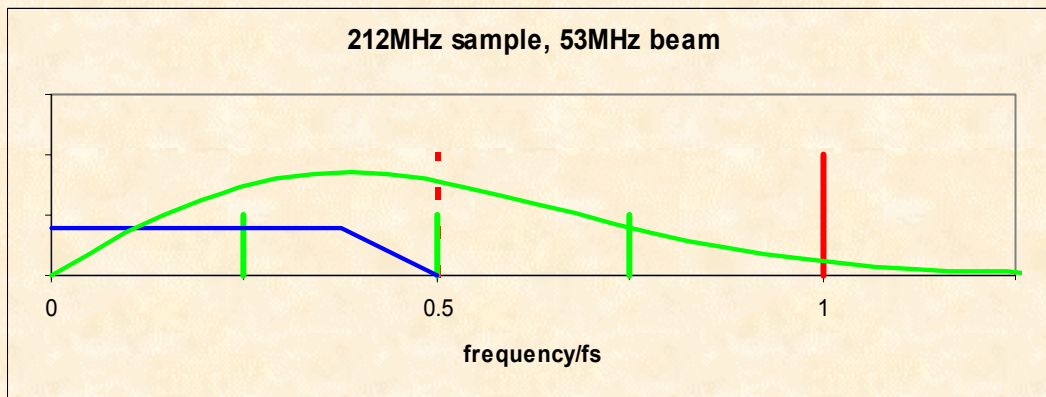
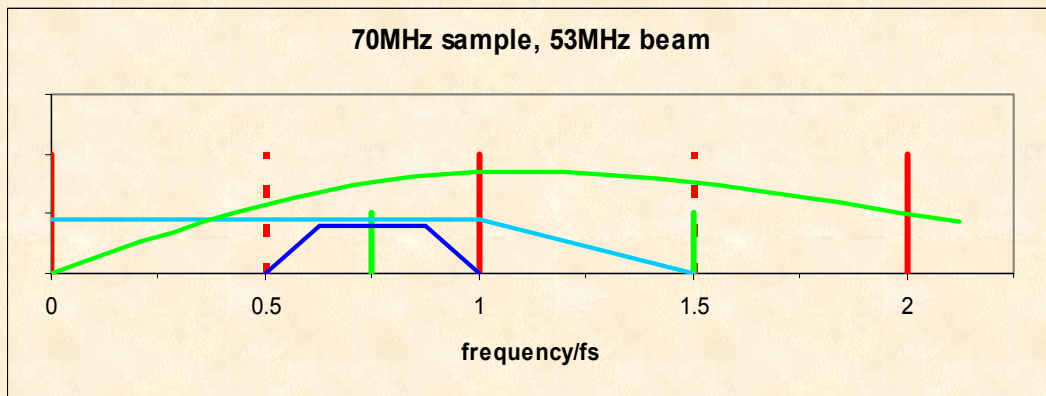
- Traditional bpm receiver isolates a single frequency component and measures the amplitude on the 2 plates
 - Wastes a lot of energy outside this bandwidth
 - Bandwidth inversely proportional to signal duration
- optimum receiver matches the frequency content of the signal
 - Use a digital filter who's coefficients match the expected signal samples (like doing an auto-correlation)
- In the Echoteks, to measure 84 bunches simply multiplied by 53MHz sinewave and summed the results
 - Timing inaccuracies required a shorter gate
- Use the impulse response of RLC filter to make optimum digital receiver for single bunch
 - (Limited bandwidth requires bunch separation)
 - (Could try splitting and summing through several cable lengths)



14bit 100MHz or 12 bit 200Mhz

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- Spectrum of sample frequencies and 53MHz beam component
- Possible filters are indicated
- Tev stripline response to 2ns sigma t bunches is also shown





12 or 14 bit?

- A/D chips available today are 14bit 100MHz and 12bit 200Mhz
- 12 bit gives up factor of 4 in resolution
 - Loose 12db of resolution or dynamic range
 - Twice as many samples provides square root of 2 noise reduction
 - Requires 75MHz lpf
- 14 bit
 - Better resolution and dynamic range
 - Square root of 2 higher noise from fewer samples
 - Requires 35MHz bpf
 - 75MHz lpf if there are no signal components in the unwanted band
- Attractive to use same Echotek card in Tevatron
 - Very fast project



Summary

- Cable impedance, vswr, attenuation, reflections, detector impedance, directionality, linearity, receiver noise, input impedance, linearity depend on frequency and limit ultimate accuracy.
- Frequency dependant errors result in time dependant position error
- I suspect noise will be small $\sim 100\mu\text{m}$ even at modest intensities
- Repeatability between identical beam and position will be about the same $< 100\mu\text{m}$
- Relative accuracy over a range of intensity, position, and bunch structure $< 1\text{mm}$
- Absolute accuracy will likely be $< 2\text{mm}$
- Sensitivity to position in the orthogonal plane may make things worse.
- Need to find a good algorithm to linearise the bpm output
- **Buying Echotek cards would provide a substantial, timely improvement for less than \$500k**